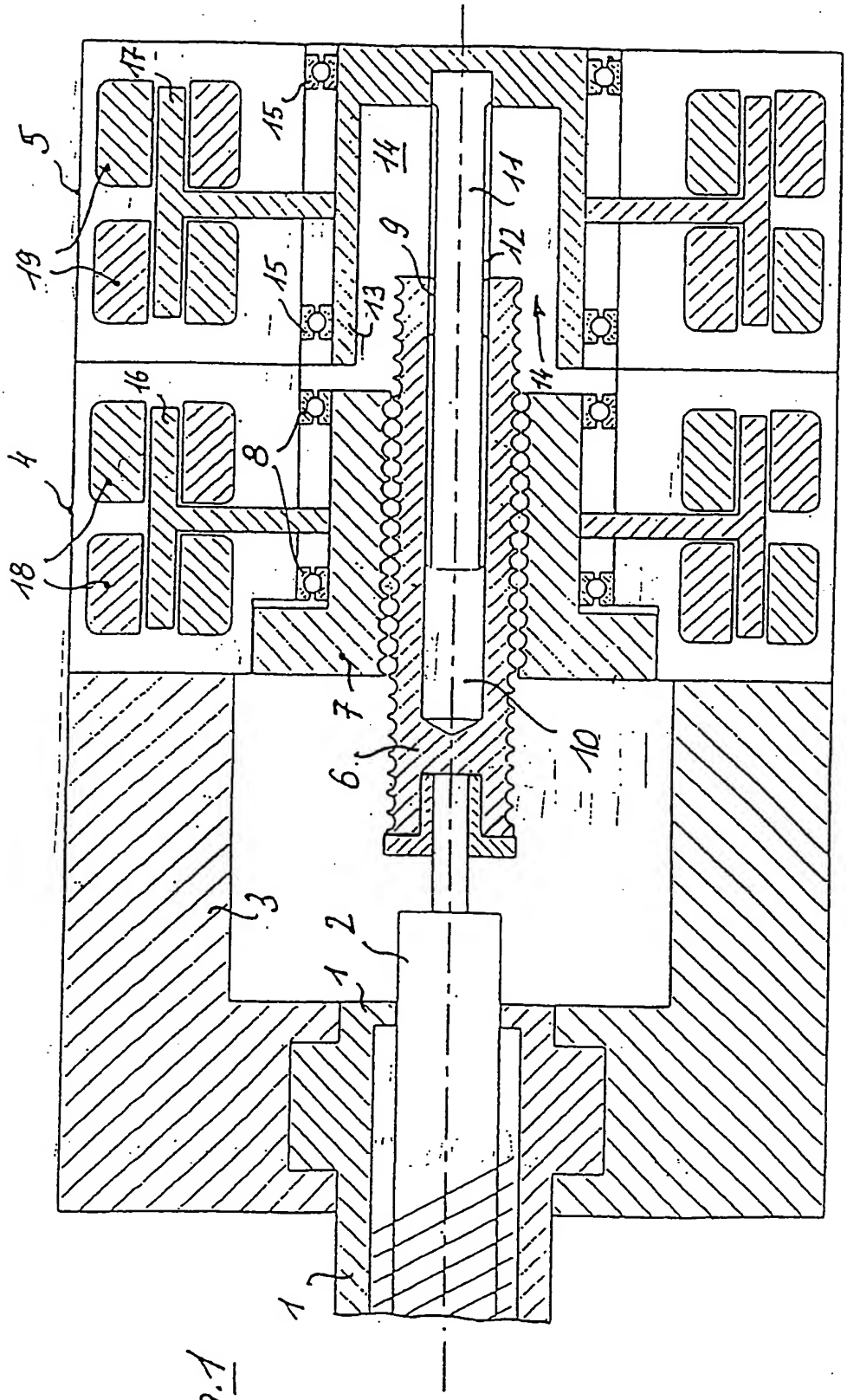
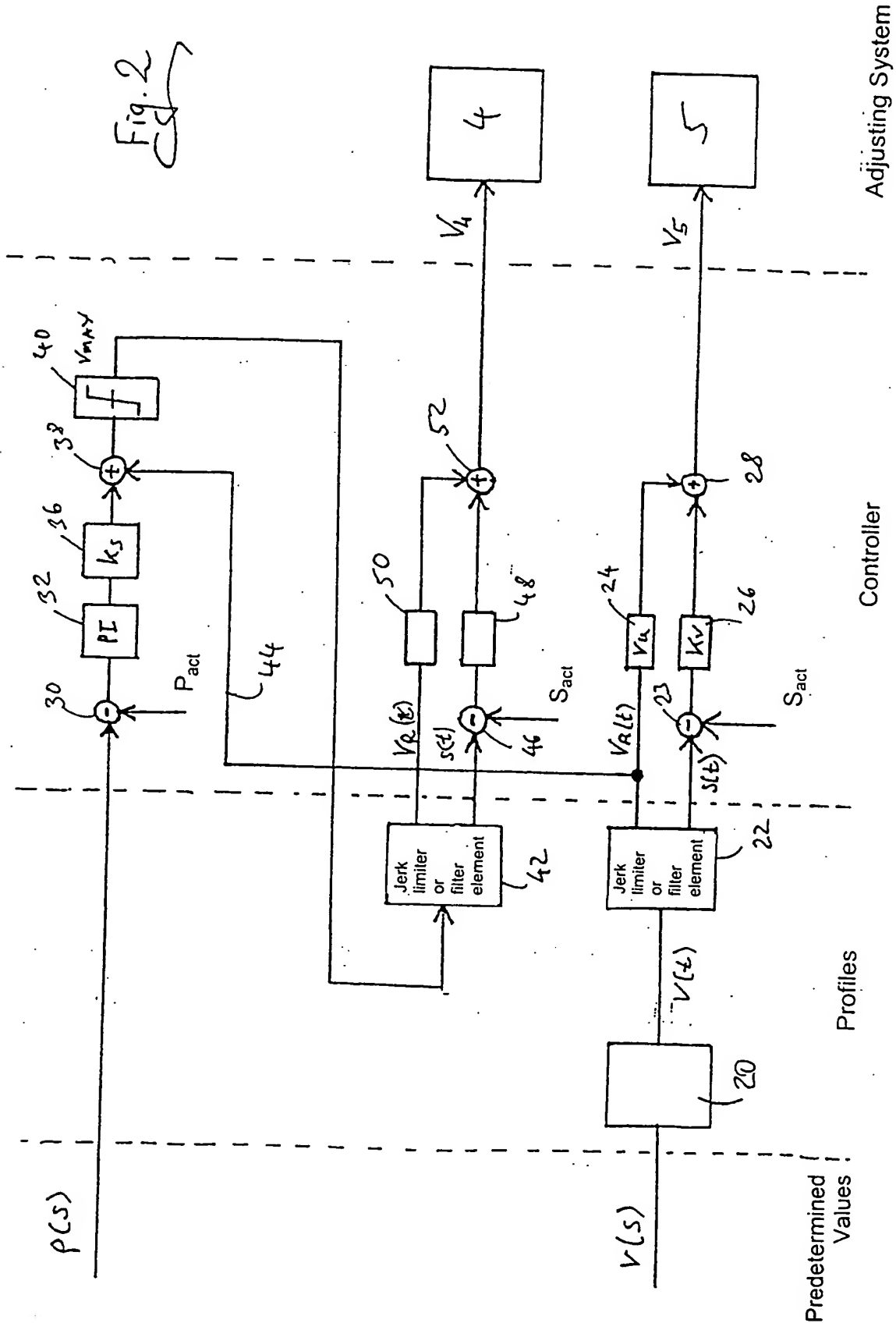


Fig.1

Fig. 2


Predetermined Values
Profiles
Controller
Adjusting System
P(s)
V(s)
20
V(t)
Jerk limiter or filter element
42
Jerk limiter or filter element
22
$V_R(t)$
$V_A(t)$
s(t)
s(t)
S_{act}
S_{act}
P_{act}
44
46
48
50
52
23
24
26
28
30
32
34
36
38
40
V_{max}
PI
k_s
V_u
k_v
V_4
V_5
4
5